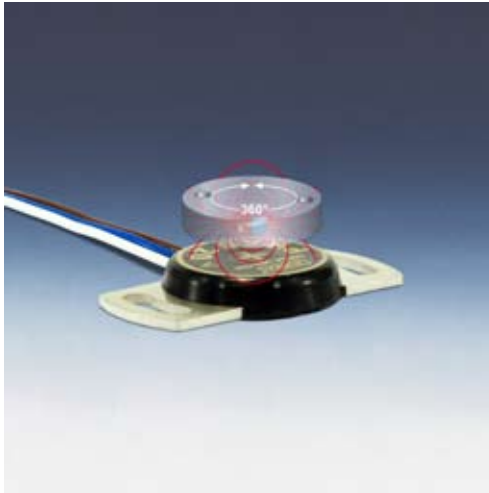


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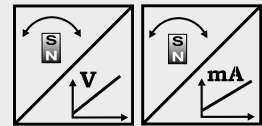
PRAS20

Magnetic Angle Sensor with Analog Output



Magnetic angle sensor 0 - 360°

- Protection class IP60
- Non-contact with external position magnet
- Wear free
- Compact, low profile housing
- Analog output
- Other outputs available on request



Specifications	Outputs	U2B	Voltage 0.5 ... 10 V
		U6	Voltage 0.5 ... 4.5 V ratiometric
		I1B	Current 4 ... 20 mA (3 wire)
	Resolution		0.03 % (60 ... 360°); 0.1 % (15 ... 45°)
	Repeatability		±0.03 % (60 ... 360°); ±0.1 % (15 ... 45°)
	Linearity		±0.5 % f.s. (typ.); a misalignment of the position magnet has an effect on the linearity (see page 30)
	Measurement range		0 ... 15° to 0 ... 360°, standard 360°
	Signal characteristics		CW, CCW
	Rated distance sensor / magnet		Depending on the position magnet, see page 30
	Material		Epoxy glass fiber, thermoplastic
	Mounting		Screws M4
	Connection		
	Protection class		IP60
	Shock		EN 60068-2-27:1993, 100 g/11 ms, 100 shocks
	Vibration		EN 60068-2-6:1995, 20 g 10 Hz-2 kHz, 10 cycles

Order Code PRAS20

Model name
PRAS20

Measurement range 15 ... 360° in 15° increments
15 / 30 / 45 / ... / 345 / 360

Output (see page 26)

U2B = 0.5 ... 10 V

U6 = 0.5 ... 4.5 V ratiometric

I1B = 4 ... 20 mA, 3 wire

Signal characteristics

CW = Signal increasing CW

CCW = Signal increasing CCW

Connection

A300 = Single wire ETFE 3 x 0.5 mm², length 300 mm

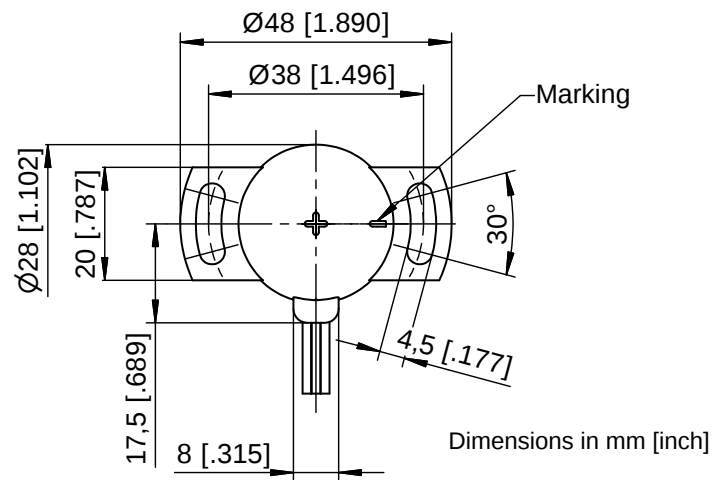
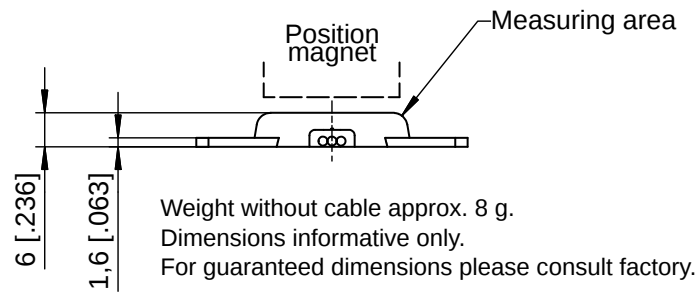
PRAS20 - [] - [] - [] - []

Order example: PRAS20 - 360 - U2B - CW - A300

POSIROT®
PRAS20
Magnetic Angle Encoder with Analog Output



Outline drawing
PRAS20



POSIROT®

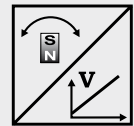
PRAS21

Magnetic Angle Sensor with Analog Output



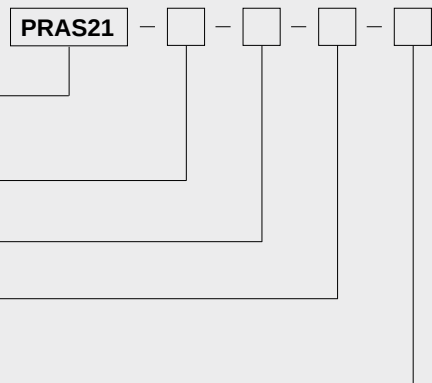
Magnetic angle sensor 0 - 360°

- Protection class IP60
- Non-contact with external position magnet
- Wear free
- Compact, low profile housing
- Analog output
- Other outputs available on request



Specifications	Outputs	U6	Voltage 0.5 ... 4.5 V ratiometric
	Resolution		0.03 % (60 ... 360°); 0.1 % (15 ... 45°)
	Repeatability		±0.03 % (60 ... 360°); ±0.1 % (15 ... 45°)
	Linearity		±0.5 % f.s. (typ.); a misalignment of the position magnet has an effect on the linearity (see page 30)
	Measurement range		0 ... 15° to 0 ... 360°, standard 360°
	Signal characteristics		CW, CCW
	Rated distance sensor / magnet		Depending on the position magnet, see page 30
	Material		Epoxy glass fiber, thermoplastic
	Mounting		Screws M3
	Connection		
	Protection class		IP60
	Shock		EN 60068-2-27:1993, 100 g/11 ms, 100 shocks
	Vibration		EN 60068-2-6:1995, 20 g 10 Hz-2 kHz, 10 cycles

Order Code PRAS21



Model name
PRAS21

Measurement range 15 ... 360° in 15° increments
15 / 30 / 45 / ... / 345 / 360

Output (see page 26)
U6 = 0.5 ... 4.5 V ratiometric

Signal characteristics
CW = Signal increasing CW
CCW = Signal increasing CCW

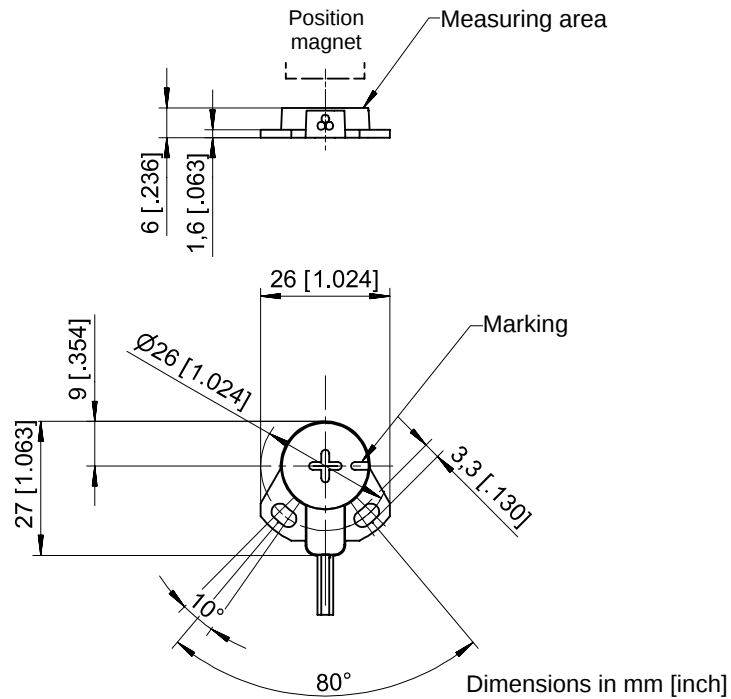
Connection
A300 = Single wire ETFE 3 x 0.5 mm², length 300 mm

Order example: PRAS21 - 360 - U6 - CW - A300

POSIROT®
PRAS21
Magnetic Angle Encoder with Analog Output



Outline drawing
PRAS21

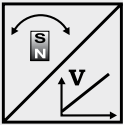


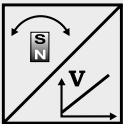
Weight without cable approx. 5 g.
Dimensions informative only.
For guaranteed dimensions please consult factory.

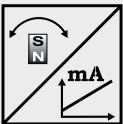
POSIROT® – PRAS, POSITILT® – PTAS

Outputs U2(B), U6 and I1(B)



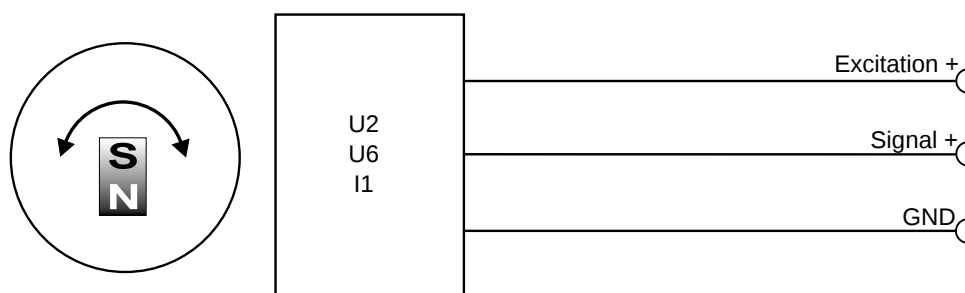
U2 / U2B Voltage Output 0.5 ... 10 V 	Excitation voltage	U2: 18 ... 36 V DC; U2B: 11.5 ... 27 V DC
	Excitation current	40 mA max.
	Output voltage	0.5 ... 10 V DC
	Output current	2 mA max.
	Measuring rate	1 kHz standard
	Stability (temperature)	$\pm 50 \times 10^{-6}$ / °C f.s. (typ.) for 90°...360° $\pm 100 \times 10^{-6}$ / °C f.s. (typ.) for <90°
	Operating temperature	-40 ... +85 °C (+105 °C as option)
	Protection	Reverse polarity, short circuit
	EMC	According to EN 61326:2004

U6 = U6/5 / U6/8,25 Voltage Output 10 ... 90 % ratiometric 	Excitation voltage	5V DC ± 10 % / 8.25 V DC ± 10 %
	Excitation current	40 mA max.
	Output voltage	10 ... 90 % of the excitation voltage
	Output current	2 mA max.
	Measuring rate	1 kHz standard
	Stability (temperature)	$\pm 50 \times 10^{-6}$ / °C f.s. (typ.) for 90°...360° $\pm 100 \times 10^{-6}$ / °C f.s. (typ.) for <90°
	Operating temperature	-40 ... +85 °C (+125 °C as option)
	Protection	Reverse polarity, short circuit
	EMC	According to EN 61326:2004

I1 / I1B Current Output 4 ... 20 mA 	Excitation voltage	I1: 18 ... 36 V DC; I1B: 10 ... 18 V DC
	Excitation current	60 mA max.
	Load resistor	I1: 500 Ω max.; I1B: 250 Ω max.
	Output current	4 ... 20 mA
	Measuring rate	1 kHz standard
	Stability (temperature)	$\pm 50 \times 10^{-6}$ / °C f.s. (typ.) for 90°...360° $\pm 100 \times 10^{-6}$ / °C f.s. (typ.) for <90°
	Operating temperature	-40 ... +85 °C
	Protection	Reverse polarity, short circuit
	EMC	According to EN 61326:2004

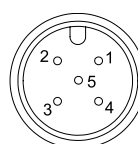
Other outputs available on request.

Output signals



Signal Wiring	Output signals	Connector pin	Cable color
	Excitation +	1	brown
	Signal	2	white
	GND	3	blue
	Do not connect!	4	black
	Do not connect!	5	–

Connection



View to sensor
connector

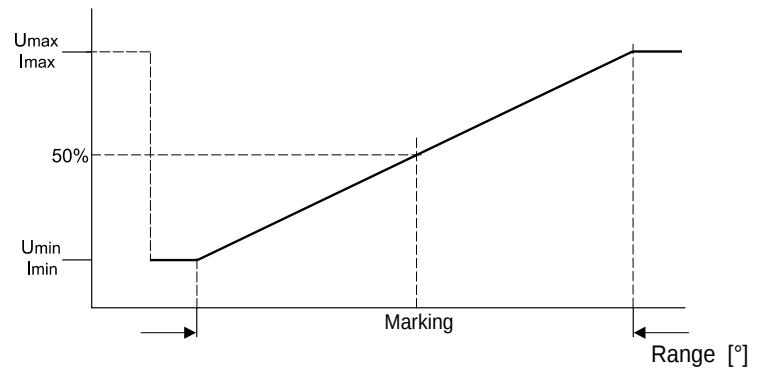
M12A5 / M12R5

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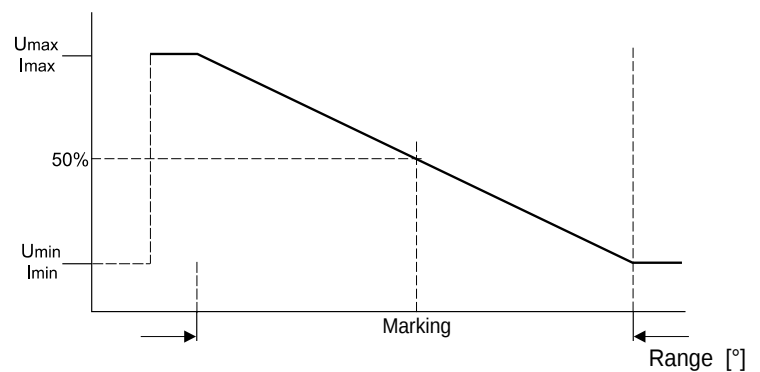
Characteristics for magnetic angle sensors



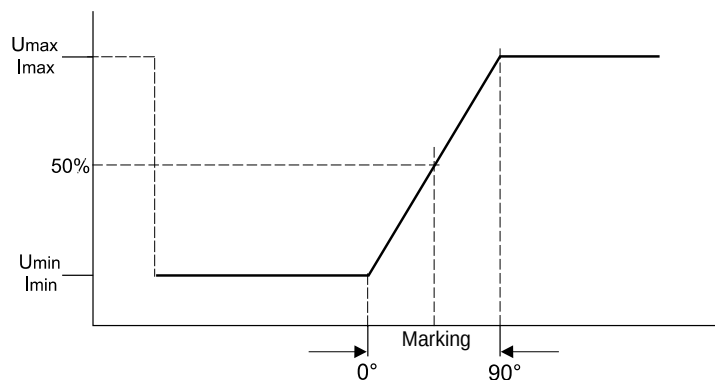
Output signal
(CW increasing)



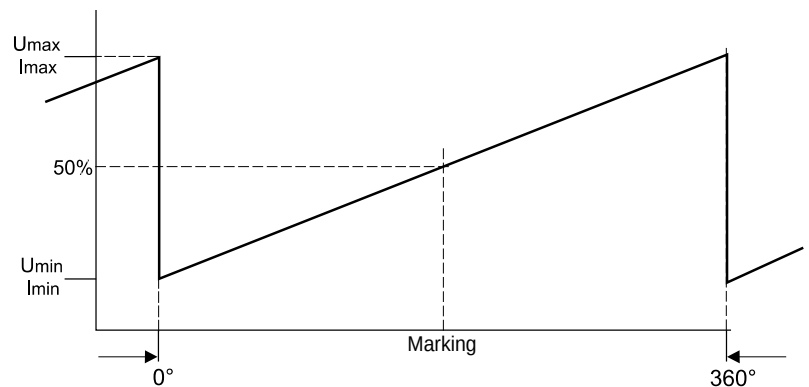
Output signal
(CCW increasing)



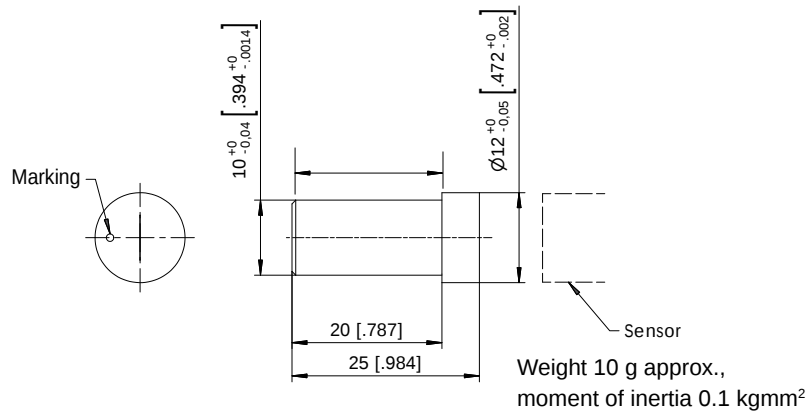
Example angular
range 90°



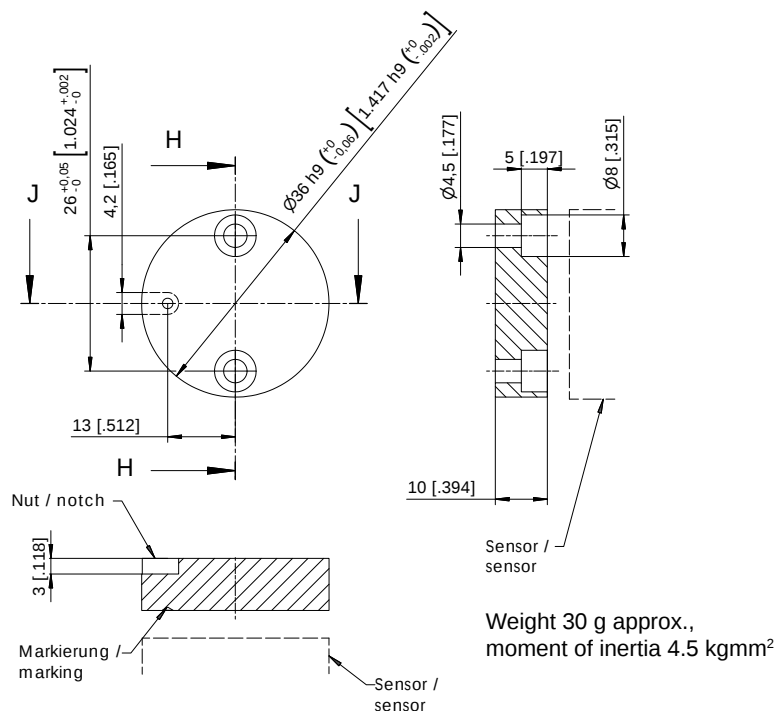
Example angular
range 360°



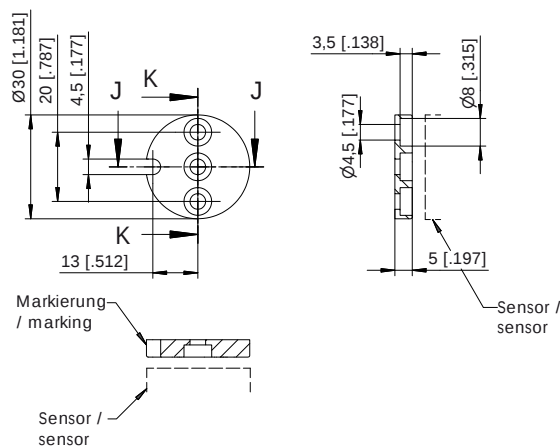
PRMAG1
PRMAG1-Z



PRMAG2
PRMAG2-Z



PRMAG20



Dimensions in mm [inch]

Dimensions informative only
For guaranteed dimensions please consult factory

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Accessories

Position magnets



Sensor	Position magnet	Air gap [mm]	Paralle- lism [°]	Error by axial misalignment [°]					
				0.2 mm	0.5 mm	1 mm	2 mm	3 mm	4 mm
PRAS1	PRMAG1	0 ... 3.5	5	0.1	0.3	2.0	13.5	–	–
	PRMAG1-Z	0 ... 4.5	5	0.1	0.3	1.5	6.5	–	–
	PRMAG20	0 ... 6.5	5	0.15	0.4	0.8	2.2	5.0	–
PRAS2	PRMAG2	0 ... 5	5	0.1	0.3	0.8	1.8	6.5	–
	PRMAG2-Z	0 ... 9	5	0.1	0.2	0.6	1.5	4.5	8.5
	PRMAG20	0 ... 6	5	0.15	0.4	0.8	2.2	5.0	–
PRAS5	PRMAG2	0 ... 4.5	5	0.1	0.3	0.8	1.8	6.5	–
	PRMAG5-Z	0 ... 7.5	5	0.1	0.2	0.6	1.5	4.5	8.5
	PRMAG20	0 ... 5.5	5	0.15	0.4	0.8	2.2	5.0	–
PRAS20	PRMAG2	0 ... 4.6	5	0.1	0.3	0.8	1.8	6.5	–
	PRMAG20	0 ... 3.5	5	0.15	0.4	0.8	2.2	5.0	–
PRAS21	PRMAG2	0 ... 3.6	5	0.1	0.3	0.8	1.8	6.5	–
	PRMAG20	0 ... 4.6	5	0.15	0.4	0.8	2.2	5.0	–

Sensor	Position magnet	Air gap [mm]	Paralle- lism [°]	Error by axial misalignment [°]					
				0.2 mm	0.5 mm	1 mm	2 mm	3 mm	4 mm
PRDS1	PRMAG1	0 ... 3	5	0.1	0.3	2.0	13.5	–	–
	PRMAG1-Z	0 ... 4	5	0.1	0.3	1.5	6.5	–	–
	PRMAG20	0 ... 4.5	5	0.15	0.4	0.8	2.2	5.0	–
PRDS2	PRMAG2	0 ... 5	5	0.1	0.3	0.8	1.8	6.5	–
	PRMAG2-Z	0 ... 7	5	0.1	0.2	0.6	1.5	4.5	8.5
	PRMAG20	0 ... 4	5	0.15	0.4	0.8	2.2	5.0	–
PRDS5	PRMAG2	0 ... 4.5	5	0.1	0.3	0.8	1.8	6.5	–
	PRMAG5-Z	0 ... 5.5	5	0.1	0.2	0.6	1.5	4.5	8.5
	PRMAG20	0 ... 3.5	5	0.15	0.4	0.8	2.2	5.0	–

Note: Sensor and position magnet must be mounted aligned!

