Rotary Measuring Technology Incremental shaft encoder



Standard Type series ESI 58L



- Many types in stock
- Sturdy model to industry standard, Ø58 mm housing
- Limited number of versions
- Temperature and ageing compensation
- Short-circuit proof outputs
- Resolution up to 5000 ppr
- High scanning rate
- (Ex) available as explosion proof zone 2 and 22

Mechanical characteristics:

Speed:	max. 12000 min ⁻¹
Rotor moment of inertia:	approx. 1.8 x 10 ⁻⁶ kgm ²
Starting torque:	< 0.01 Nm
Radial load capacity of shaft*:	80 N
Axial load capacity of shaft:*:	40 N
Weight:	approx. 0.4 kg
Protection acc. to EN 60 529:	IP 65
Working temperature:	−20 °C +70 °C ¹⁾
Operating temperature:	–20 °C +75 °C ¹⁾
Shaft:	stainless steel
Shock resistance acc. to DIN-IEC 68-2-27	1000 m/s ² , 6 ms
Vibration resistance acc. to DIN-IEC 68-2-6:	100 m/s ² , 102000 Hz

^{*} View also diagrams on page 25

2) Non-condensing

Pulse rates available at short notice:

10, 20, 25, 30, 50, 60, 100, 120, 125, 127, 150, 180, 200, 216, 240, 250, 254, 256, 300, 314, 360, 375, 400, 500, 512, 600, 625, 720, 745, 750, 762, 800, 900, 927, 1000, 1024, 1250, 1270, 1400, 1500, 1800, 2000, 2048, 2250, 2400, 2500, 3000, 3600, 4000, 4096, 5000

Other pulse rates on request

Electrical characteristics:

Output circuit:	RS 422	Push-pull	Push-pull					
	(TTL-compatible)							
Supply voltage:	5 V (±5 %) or 10 30 V DC	10 30 V DC	5 30 V DC					
Power consumption (no load)	-	typ. 55 mA /	typ. 55 mA /					
without inverted signal:		max. 125 mA	max. 125 mA					
Power consumption (no load)	typ. 40 mA /	typ. 80 mA/	Typ. 80 mA					
with inverted signals:	max. 90 mA	max. 150 mA	max. 150 mA					
Permissible load/channel:	max. ±20 mA	max. ±30 mA	max. ±30 mA					
Pulse frequency:	max. 300 kHz	max. 300 kHz	max. 300 kHz					
Signal level high:	min. 2.5 V	min. U _B -2.5 V	min. U _B -1.5 V					
Signal level low:	max. 0.5 V	max. 2.0 V	max. 2.0 V					
Rise time t _r	max. 200 ns	max. 1 μs	max. 1 μs					
Fall time t _f	max. 200 ns	max. 1 μs	max. 1 μs					
Short circuit proof outputs: ¹⁾ :	yes ²⁾	yes	yes					
Reverse connection protection at U _B :	no	yes	no					
Conforms to CE requirements acc. to EN 61000-6-1, EN 61000-6-4 and EN 61000-6-3								

¹⁾ If supply voltage correctly applied

2) Only one channel allowed to be shorted-out:

(If UB=5 V, short-circuit to channel, 0 V, or +UB is permitted.)

(If UB=5-30 V, short-circuit to channel or 0 V is permitted.)

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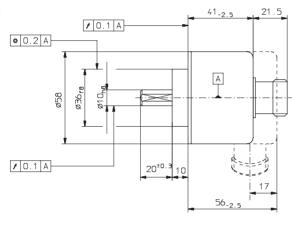
Terminal assignment

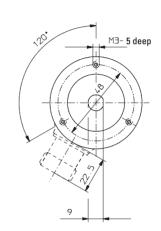
Signal:	0V	0V	+U _B	+U _B	Α	A	В	B	0	0	Shield
		Sensor ²⁾	_	Sensor ²⁾							
12 pin plug, Pin:	10	11	12	2	5	6	8	1	3	4	PH ¹⁾
7 pin plug, Pin:	F	-	D	E	Α	-	В	_	С	-	G
10 pin plug, Pin:	F	-	D	E	Α	G	В	Н	С	I	J
Cable colour:	WH	GY PK	BN	RD BU	GN	YE	GY	PK	BU	RD	

¹⁾ PH = Shield is attached to connector housing

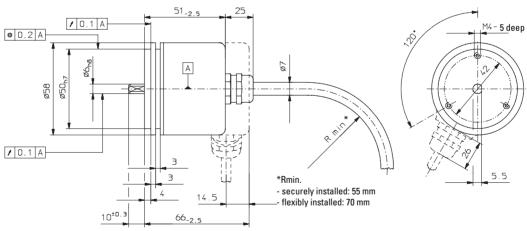
Dimensions

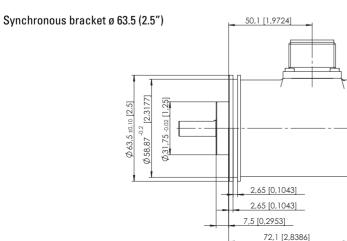
Clamping bracket ø 58

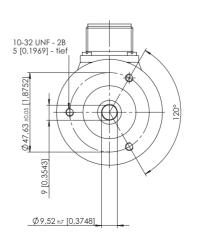




Synchronous bracket ø







The brackets and shafts of the encoder and drive should not both be rigidly coupled together at the same time! We recommend the use of suitable couplings (see Accessories

section)

Mounting advice:

Sensor cables are connected to the supply voltage internally if long feeder cables are involved they can be used to adjust or control the voltage at the encoder

⁻ If sensor cables are not in use, they have to be insulated or 0 $\rm V_{Sensor}$ has to be connected to 0 V and $\rm U_{BSensor}$ has to be connected to U_B

Using RS 422 outputs and long cable distances, a wave impedance has to be applied at each cable end.

Insulate unused outputs before initial startup.

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